

**Worksheet n°3: Multiple time-scale analysis and amplitude equations**1/ Direct numerical simulation of cylinder flow at  $Re=100$ 

We solve the unsteady Navier-Stokes equations in perturbative form ( $w := w_0 + w$ ) around a cylinder flow at  $Re = \nu^{-1} = 100$ . The initial condition is the real part of a small amplitude unstable global mode.

$$\mathcal{B}\partial_t w + \mathcal{N}_{w_0} w + \mathcal{L}w = -\frac{1}{2}\mathcal{N}(w, w)$$

$$w(0) = \alpha \text{Re}(\hat{w})$$

with :

$$w = \begin{pmatrix} u \\ v \\ p \end{pmatrix}, \mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \mathcal{N}(w_1, w_2) = \begin{pmatrix} u_1 \cdot \nabla u_2 + u_2 \cdot \nabla u_1 \\ 0 \end{pmatrix}, \mathcal{N}_{w_0} w = \mathcal{N}(w_0, w),$$

$$\mathcal{L} = \begin{pmatrix} -\nu \Delta \mathcal{O} & \nabla \mathcal{O} \\ -\nabla \cdot \mathcal{O} & 0 \end{pmatrix}$$

The base-flow and the global mode are defined by:

$$\frac{1}{2}\mathcal{N}(w_0, w_0) + \mathcal{L}w_0 = 0$$

$$\lambda \mathcal{B}\hat{w} + (\mathcal{N}_{w_0} + \mathcal{L})\hat{w} = 0$$

In DNS/Mesh:

```
FreeFem++ mesh.edp
```

In DNS/BF:

```
FreeFem++ init.edp
```

```
FreeFem++ newton.edp
```

In DNS/Eigs:

```
FreeFem++ eigen.edp
```

In DNS/DNS:

```
FreeFem++ init.edp // generate initial condition from small amplitude global mode
```

```
FreeFem++ dns.edp // launch DNS simulation
```

```
Octave plotlinlog('out_0.txt',1,2,1) // represent energy as a function of time in fig 1
```

```
Octave plotlinlin('out_0.txt',1,4,2) // represent v velocity as a function of time
```

## 2/ Van der Pol Oscillator: multiple time-scale analysis

The Van der Pol Oscillator corresponds to the following governing equations:

$$w'' + \omega_0^2 w = 2\tilde{\delta}w' - w^2w'$$

$$w(0) = w_I, w'(0) = 0$$

where the  $(\cdot)'$  is the time-derivative,  $w_I$  is the initial condition,  $\omega_0$  the frequency and  $\tilde{\delta}$  the instability strength. Here, we choose:  $\omega_0 = 10$ ,  $\tilde{\delta} = 0.3$  and  $w_I = 0.01$ .

## 2a/ Numerical time-integration

We integrate in time the above equations. For this,

In VanDerPol:

```
Octave pkg load all // load external packages for time integration, Fourier analysis, etc.
```

```
Octave vdp // integrate in time unforced Van der Pol equations
```

## 2b/ One time-scale approach

We try to approximate the solution by considering a small instability strength:  $\tilde{\delta} = \delta\epsilon$ , with  $\epsilon \ll 1$  and  $\delta = O(1)$ . We look for an approximation of the solution with an expansion of the form:

$$w = \epsilon^{\frac{1}{2}}y \text{ and } y = y_0 + \epsilon y_1 + \dots$$

We first try with only one time-scale:  $y(t) = y_0(t) + \epsilon y_1(t) + \dots$

The second-order solution is given by:

$$w = (\tilde{A}e^{i\omega_0 t} + \text{c. c.}) + \left( \frac{-3\tilde{A}^3 + 12\tilde{\delta}\tilde{A}}{8\omega_0} ie^{i\omega_0 t} + \frac{i\tilde{A}^3}{8\omega_0} e^{3i\omega_0 t} - (2\tilde{\delta}\tilde{A} - \tilde{A}^3) \left( \frac{1 + 2i\omega_0 t}{4\omega_0} \right) ie^{i\omega_0 t} + \text{c. c.} \right)$$

$$\tilde{A} = \frac{w_I}{2}$$

To represent this solution, in VanDerPol:

```
Octave clf // clear all figures
```

```
Octave vdp // integrate in time unforced Van der Pol equations
```

```
Octave vdp_tlr // show first and second order approximations with one time-scale
```

## 2c/ Two time-scales approach

The two time-scale first-order solution is given by:

$$w(t) = (\tilde{A}e^{i\omega_0 t} + \text{c. c.})$$

with:

$$\frac{d\tilde{A}}{dt} = \tilde{\delta}\tilde{A} - \frac{1}{2}\tilde{A}^3$$

$$\tilde{A}(0) = \frac{w_I}{2}$$

To represent this solution, in VanDerPol:

Octave clf // clear all figures

Octave vdp // integrate in time unforced Van Der Pol equations

Octave vdp\_tlr // show first and second order approximations with one time-scale

Octave vdp\_mts // show first and second order approximations with two time-scales

3/ Van der Pol Oscillator with harmonic forcing

We consider the forced Van der Pol oscillator:

$$w'' + \omega_0^2 w = 2\tilde{\delta}w' - w^2w' + \tilde{E} \cos \omega_f t,$$

where  $\omega_f$  and  $\tilde{E}$  are respectively the forcing frequency and the forcing amplitude. Here, we choose:  $\omega_f = 25$  and  $\tilde{E} = 600$ . The first-order two time-scale solution is given by:

$$w(t) = 2\tilde{A} \cos(\omega_0 t + \phi) + \frac{\tilde{E}}{\omega_0^2 - \omega_f^2} \cos \omega_f t$$

with:

$$\frac{d\tilde{A}}{dt} = \left[ \tilde{\delta} - \frac{1}{4} \left( \frac{\tilde{E}}{\omega_0^2 - \omega_f^2} \right)^2 \right] \tilde{A} - \frac{1}{2} \tilde{A}^3$$

To represent this solution, in VanDerPol:

Octave clf // clear all figures

Octave vdpf // integrate in time unforced Van Der Pol equations

Vary the forcing amplitude  $\tilde{E}$  from 0 to 600 and observe in each case the resulting frequency spectrum.

4/ Forced Navier-Stokes equations

We consider the Navier-Stokes equation in perturbative form ( $w = w_0 + w$ ) with a forcing term acting on the momentum equations:

$$\mathcal{B}\partial_t w + \mathcal{N}_{w_0} w + \mathcal{L}w = \tilde{\delta}\mathcal{M}(w_0 + w) - \frac{1}{2}\mathcal{N}(w, w) + (\tilde{E}e^{i\omega_f t} f + c.c.).$$

Here:

$$w = \begin{pmatrix} u \\ v \\ p \end{pmatrix}, \mathcal{L} = \begin{pmatrix} -\nu_c \Delta & 0 \\ -\nabla \cdot & 0 \end{pmatrix}, \mathcal{M} = \begin{pmatrix} -\Delta & 0 \\ 0 & 0 \end{pmatrix}.$$

The viscosity  $\nu$  has been replaced by  $\nu = \nu_c - \delta$ , where  $\nu_c$  is the critical viscosity which achieves marginal stability of the linear dynamics  $Re_c = \nu_c^{-1} = 46.6$ .

The base-flow is given by:

$$\frac{1}{2} \mathcal{N}(w_0, w_0) + \mathcal{L}w_0 = 0,$$

while  $\tilde{E}$  and  $\omega_f$  correspond respectively to the forcing amplitude and forcing frequency. The forcing structure  $f$  (acting solely on the momentum equations, so that  $\mathcal{B}f = f$ ) is also given.

In the following, we consider a slightly supercritical regime (the Reynolds number is slightly above the critical Reynolds number):

$$\delta = \epsilon \delta, \quad \epsilon \ll 1, \quad \delta = O(1),$$

and a small- amplitude forcing, which scales as:

$$\tilde{E} = \epsilon^{\frac{1}{2}} E, \quad E = O(1).$$

We look for an approximation of the solution under the form:

$$w = \epsilon^{\frac{1}{2}} \left( y_0(t, \tau = \epsilon t) + \epsilon^{\frac{1}{2}} y_1(t, \tau = \epsilon t) + \epsilon^1 y_1(t, \tau = \epsilon t) + \dots \right)$$

The second-order solution is given by:

$$w = (\tilde{A} e^{i\omega_c t} y_A + \text{c. c.}) + (\tilde{E} e^{i\omega_f t} y_E + \text{c. c.}) + \delta w_\delta + (\tilde{A}^2 e^{2i\omega_c t} y_{AA} + \text{c. c.}) + |\tilde{A}|^2 y_{A\bar{A}} + |\tilde{E}|^2 y_{E\bar{E}} \\ + (\tilde{A} \tilde{E} e^{i(\omega_c + \omega_f)t} y_{AE} + \text{c. c.}) + (\tilde{A} \tilde{E} e^{i(\omega_c - \omega_f)t} y_{A\bar{E}} + \text{c. c.}) + \dots$$

With :

$$i\omega_c \mathcal{B}y_A + \mathcal{N}_{w_0} y_A + \mathcal{L}y_A = 0$$

$$i\omega_f \mathcal{B}y_E + \mathcal{N}_{w_0} y_E + \mathcal{L}y_E = f$$

$$\mathcal{N}_{w_0} y_\delta + \mathcal{L}y_\delta = \mathcal{M}y_0$$

$$2i\omega_c \mathcal{B}y_{AA} + \mathcal{N}_{w_0} y_{AA} + \mathcal{L}y_{AA} = -\frac{1}{2} \mathcal{N}(y_A, y_A)$$

$$\mathcal{N}_{w_0} y_{A\bar{A}} + \mathcal{L}y_{A\bar{A}} = -\mathcal{N}(y_A, \bar{y}_A)$$

$$\mathcal{N}_{w_0} y_{E\bar{E}} + \mathcal{L}y_{E\bar{E}} = -\mathcal{N}(y_E, \bar{y}_E)$$

$$2i(\omega_c + \omega_f) \mathcal{B}y_{AE} + \mathcal{N}_{w_0} y_{AE} + \mathcal{L}y_{AE} = -\mathcal{N}(y_A, y_E)$$

$$2i(\omega_c - \omega_f) \mathcal{B}y_{A\bar{E}} + \mathcal{N}_{w_0} y_{A\bar{E}} + \mathcal{L}y_{A\bar{E}} = -\mathcal{N}(y_A, \bar{y}_E)$$

And:

$$\frac{d\tilde{A}}{dt} = \lambda\tilde{\delta}\tilde{A} - \mu\tilde{A}|\tilde{A}|^2 - \pi\tilde{A}|\tilde{E}|^2$$

where:

$$\begin{aligned}\lambda &= \langle \tilde{y}_A, \mathcal{M}y_A \rangle - \langle \tilde{y}_A, \mathcal{N}(y_A, y_\delta) \rangle \\ \mu &= \langle \tilde{y}_A, \mathcal{N}(y_A, y_{AA}) + \mathcal{N}(\bar{y}_A, y_{AA}) \rangle \\ \pi &= \langle \tilde{y}_A, \mathcal{N}(y_A, y_{E\bar{E}}) + \mathcal{N}(y_{\bar{E}}, y_{AE}) + \mathcal{N}(y_E, y_{A\bar{E}}) \rangle \\ &\quad - i\omega_c \mathcal{B}\tilde{y}_A + \tilde{\mathcal{N}}_{w_0}\tilde{y}_A + \tilde{\mathcal{L}}\tilde{y}_A = 0 \\ &\quad \langle \tilde{y}_A, \mathcal{B}y_A \rangle = 1\end{aligned}$$

4a/ In Ampleq/Mesh:

```
FreeFem++ mesh.edp // generate mesh
```

In Ampleq/BF:

```
FreeFem++ init.edp // generate initial guess for Newton iterations
```

```
FreeFem++ newton.edp // Newton iteration
```

In Ampleq/Eigs:

```
FreeFem++ eigen.edp // compute global mode
```

```
FreeFem++ eigenadj.edp // compute adjoint global mode
```

```
FreeFem++ norm.edp // generate scaled adjoint global mode
```

In Ampleq/WNL:

```
FreeFem++ udelta.edp // generate modification of base-flow due to increase in Reynolds
number
```

```
FreeFem++ uAA.edp // generate second harmonic due to interaction of global mode with
himself
```

```
FreeFem++ uAAb.edp // generate zero-harmonic due to interaction of global mode with
adjoint of himself
```

```
FreeFem++ lambda.edp // compute λ coefficient of Stuart-Landau equation
```

```
FreeFem++ mu.edp // compute μ coefficient of Stuart-Landau equation
```

```
FreeFem++ forcing.edp // define external forcing (spatial structure and frequency)
```

```
FreeFem++ uE.edp // compute response due to external forcing
```

```
FreeFem++ uAE.edp // compute AE-harmonic due to interaction of response to
                    external forcing with global mode
```

4b/ Complete program uAEb.edp to compute the  $A\bar{E}$  harmonic due to the interaction of the global mode with the adjoint of the response due to external forcing.

4c/ Complete program uEEb.edp to compute the zero-harmonic due to the interaction of the external forcing response with the conjugate of himself.

4d/ Complete program pi.edp to compute the  $\pi$  coefficient.

5/ Forced Direct numerical simulation

We integrate in time the forced Navier-Stokes equations at  $Re = \nu^{-1} = 100$ :

$$\mathcal{B}\partial_t w + \mathcal{N}_{w_0} w + \mathcal{L}w = -\frac{1}{2}\mathcal{N}(w, w) + (\tilde{E}e^{i\omega_f t} f + c. c)$$

where:

$$w = \begin{pmatrix} u \\ v \\ p \end{pmatrix}, \mathcal{L} = \begin{pmatrix} -\nu \Delta \mathcal{O} & \nabla \mathcal{O} \\ -\nabla \cdot \mathcal{O} & 0 \end{pmatrix}$$

In DNS/DNS:

```
FreeFem++ dnsf.edp // launch forced DNS simulation
```

```
Octave plotlinlog('out_4000.txt',1,2,1) // represent energy as a function of time in fig 1
```

```
Octave plotlinlin('out_4000.txt',1,4,2) // represent v velocity as a function of time in fig 2
```

```
Octave spectrum // compare spectrum with and without control
```