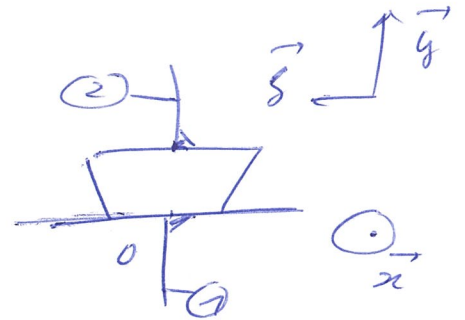
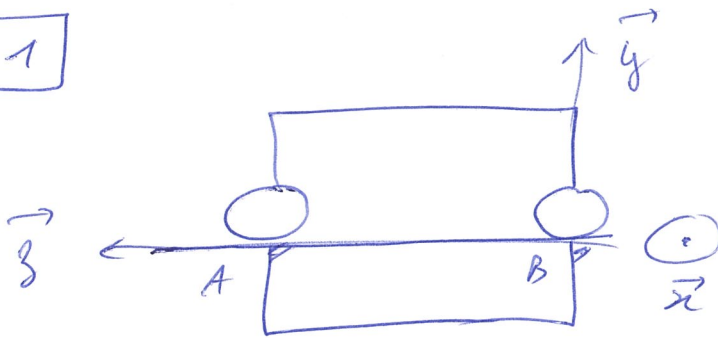


DS NPSI, mars 23

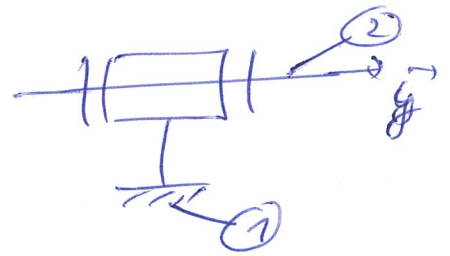
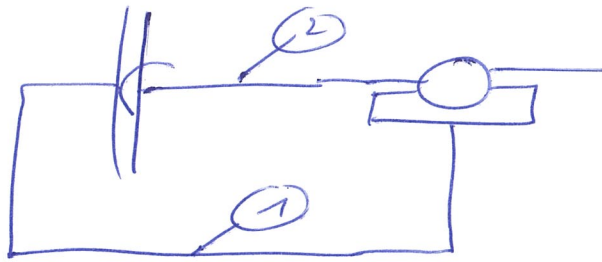
Exo 1



$$\{v_{2/1}\} = \begin{Bmatrix} 0 & u \\ \delta & 0 \\ \gamma & w \end{Bmatrix}_O$$

Lineaire annulaire
Sphère cylindre plan

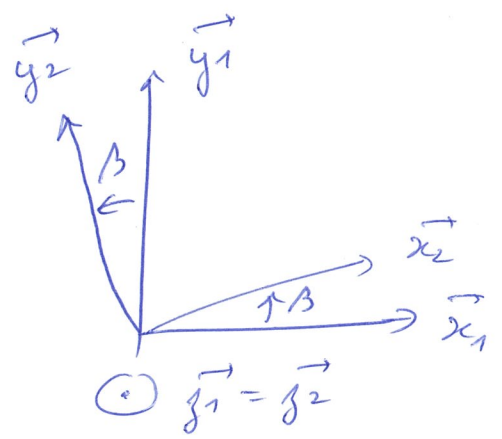
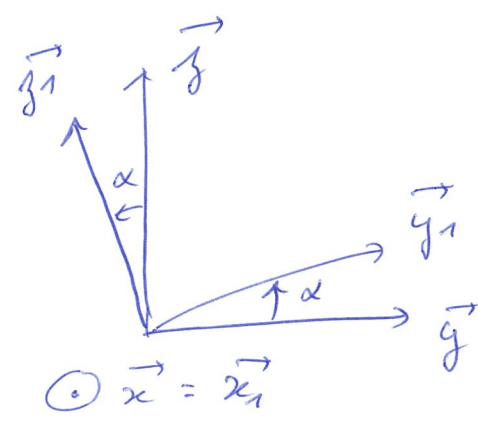
Exo 2



$$\{v\} = \begin{Bmatrix} 0 & 0 \\ 0 & v \\ 0 & 0 \end{Bmatrix}_A$$

Exo 3

Q1



Q2 $\{v_{%0}\} = \left\{ \begin{matrix} \Omega_{%0}^{\vec{z}} \\ \vec{v}(B \in \%0) \end{matrix} \right\}_B$

$\Omega_{%0}^{\vec{z}} = \dot{\alpha} \vec{x}_1 + \dot{\beta} \vec{y}_1$

$\vec{v}(B \in \%0) = \left(\frac{d\vec{OB}}{dt} \right)_0$

$\vec{OB} = \vec{OA} + \vec{AB} = r \vec{y}_1 + l \vec{x}_2$

$\left(\frac{d\vec{x}_2}{dt} \right)_0 = \left(\frac{d\vec{x}_2}{dt} \right)_1 + \Omega_{%0}^{\vec{z}} \wedge \vec{x}_2$

$= \dot{\beta} \vec{y}_2 + \dot{\alpha} \vec{x}_1 \wedge (\cos \beta \vec{x}_1 + \sin \beta \vec{y}_1)$

$= \dot{\beta} \vec{y}_2 + \dot{\alpha} \sin \beta \vec{z}_1 \quad (\times l)$

$\vec{v}(B \in \%0) = r \dot{\alpha} \vec{y}_1 + l \dot{\alpha} \sin \beta \vec{z}_1 + l \dot{\beta} \vec{y}_2$

$= l \dot{\beta} \vec{y}_2 + (r + l \sin \beta) \dot{\alpha} \vec{z}_1$

$= \vec{v}(B \in \%1) + \vec{v}(B \in \%0)$

Q3 $\left. \begin{matrix} \vec{AC} = \vec{AB} + \vec{BC} \\ r \vec{x} = l \vec{x}_2 + l \vec{x}_3 \end{matrix} \right\} \Rightarrow r = 2l \cos \beta$

③ **Exo 4** (Q1) y varie de 0 à $(R_2 - a)$

$$\textcircled{Q2} \vec{v}(B \in \frac{3}{2}) = \vec{0} = \vec{v}(B \in \frac{3}{1}) + \vec{v}(B \in \frac{1}{2})$$

$$\begin{aligned} \vec{v}(B \in \frac{2}{1}) &= \vec{v}(A \in \frac{2}{1}) + \Omega_{\frac{2}{1}} \wedge \vec{AB} \\ &= \vec{0} + \omega_2 \vec{x} \wedge (-x \vec{x} + y \vec{y}) \\ &= y \omega_2 \vec{z} \end{aligned}$$

$$\begin{aligned} \vec{v}(B \in \frac{3}{1}) &= \vec{v}(E \in \frac{3}{1}) + \Omega_{\frac{3}{1}} \wedge \vec{EB} \\ &= \vec{0} + \omega_3 \vec{y} \wedge (-2x \vec{x}) \\ &= -2\omega_3 \vec{z} \end{aligned}$$

$$\Rightarrow y \omega_2 = -2\omega_3 \Rightarrow \boxed{\omega_3 = -\frac{y}{2} \omega_2}$$

$$\textcircled{Q3} \vec{v}(C \in \frac{4}{3}) = \vec{0} = \vec{v}(C \in \frac{4}{1}) + \vec{v}(C \in \frac{1}{3})$$

$$\begin{aligned} \vec{v}(C \in \frac{4}{1}) &= \vec{v}(D \in \frac{4}{1}) + \Omega_{\frac{4}{1}} \wedge \vec{DC} \\ &= \vec{0} + \omega_4 \vec{x} \wedge [-(a+y) \vec{x} + (a+y) \vec{y}] \\ &= -(a+y) \omega_4 \vec{z} \end{aligned}$$

$$\begin{aligned} \vec{v}(C \in \frac{3}{1}) &= \vec{v}(E \in \frac{3}{1}) + \Omega_{\frac{3}{1}} \wedge \vec{EC} \\ &= \vec{0} + \omega_3 \vec{y} \wedge 2x \vec{x} \\ &= 2\omega_3 \vec{z} \end{aligned}$$

$$\Rightarrow -(a+y) \omega_4 = 2\omega_3 \Rightarrow \boxed{\omega_4 = -\frac{2}{a+y} \omega_3}$$

$$\textcircled{Q4} \boxed{\omega_4 = -\frac{y}{a+y} \omega_2}$$