

Correction DS de SE, MPSI 1, oct 24

Exo 1 $H(\lambda) = \frac{3}{\lambda+5}$ $E(\lambda) = \frac{1}{\lambda}$ $S(\lambda) = \frac{3}{\lambda(\lambda+5)}$

$S(\lambda) = \frac{a}{\lambda} + \frac{b}{\lambda+5}$ $3 = a(\lambda+5) + b\lambda = (a+b)\lambda + 5a$

$a = \frac{3}{5}$ $b = -\frac{3}{5}$ $S(\lambda) = \frac{3}{5} \left(\frac{1}{\lambda} - \frac{1}{\lambda+5} \right)$

$s(t) = \frac{3}{5} (1 - e^{-5t}) \cdot u(t)$

Exo 2 $H(\lambda) = \frac{5}{\lambda^2 + 5\lambda + 11}$ $E(\lambda) = 1$

$S(\lambda) = \frac{5}{\lambda^2 + 5\lambda + 11} = \frac{5 \times \frac{1}{3} \times 3}{(\lambda+2)^2 + 7}$

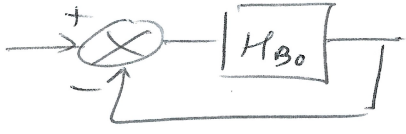
$s(t) = \frac{5}{\sqrt{7}} e^{-2t} \sin(\sqrt{7}t) \cdot u(t)$

Exo 3 $\Delta(\infty) = 8$ $1,05 \Delta(\infty) = 8,4$ $t_{5\%} = 53 \text{ s}$
 $0,95 \Delta(\infty) = 7,6$

Exo 4 (Q3) $H_1(\lambda) = \frac{1}{R+L\lambda}$ $K_2 = K_{in}$ $H_3(\lambda) = \frac{1}{J\lambda}$ $K_3 = K_{in}$

(Q4) $\Omega_f(\lambda) = \frac{1}{J\lambda} (C_f(\lambda) + C_e(\lambda)) \Rightarrow C_3(\lambda) = \frac{1}{J\lambda}$

$G_1(\lambda) = b$ $C_e(\lambda) = \frac{b}{\lambda} [\Omega_m(\lambda) - \Omega_f(\lambda)] \Rightarrow G_2(\lambda) = \frac{b}{\lambda}$

(Q5)  $H_{B0}(\lambda) = \left(b + \frac{b}{\lambda} \right) \frac{1}{J\lambda} = \frac{b\lambda + b}{J\lambda^2}$

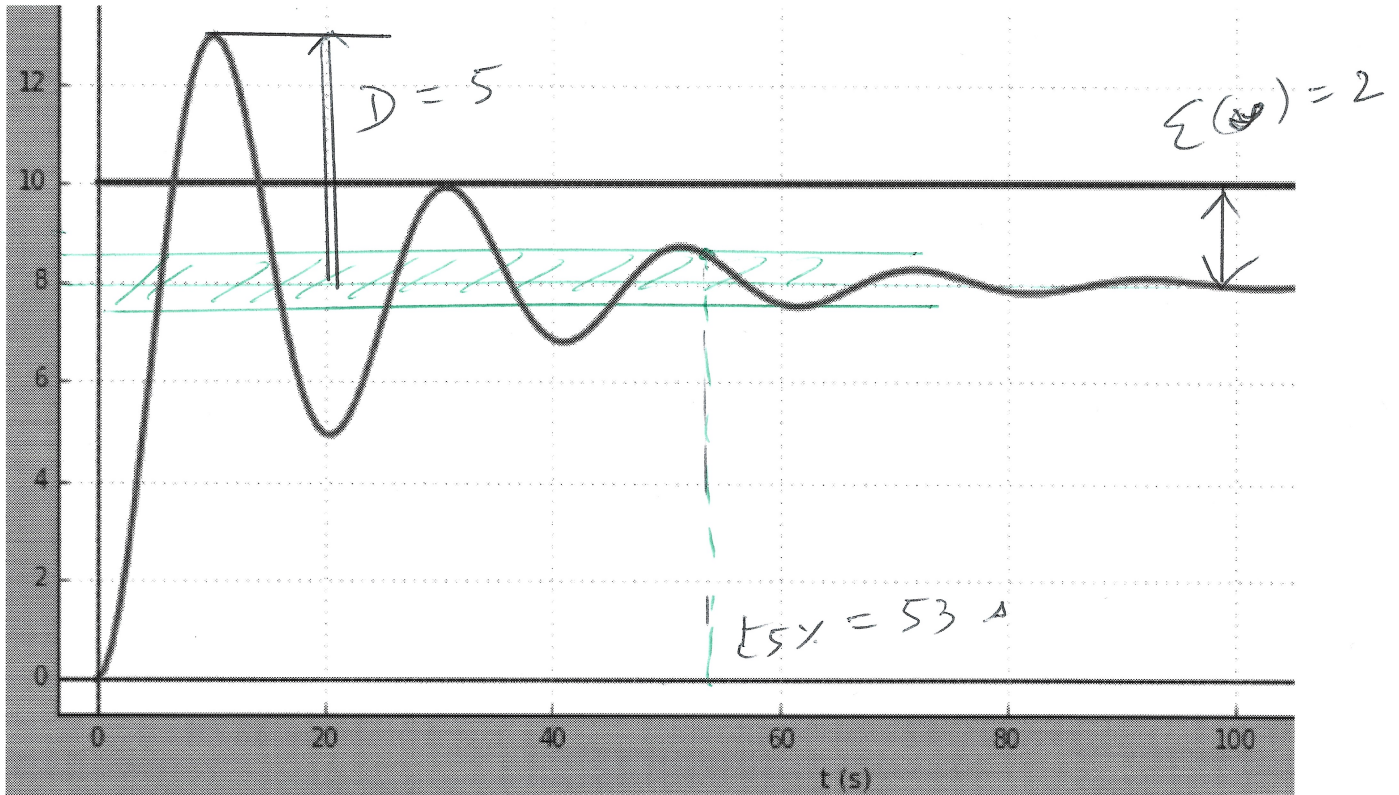
$H_{B0F}(\lambda) = \frac{b\lambda + b}{J\lambda^2 + b\lambda + b}$

(Q3) Suete
 $H_{suete} = \frac{K_{in}}{(R+L\lambda)J\lambda + K_{in}^2}$

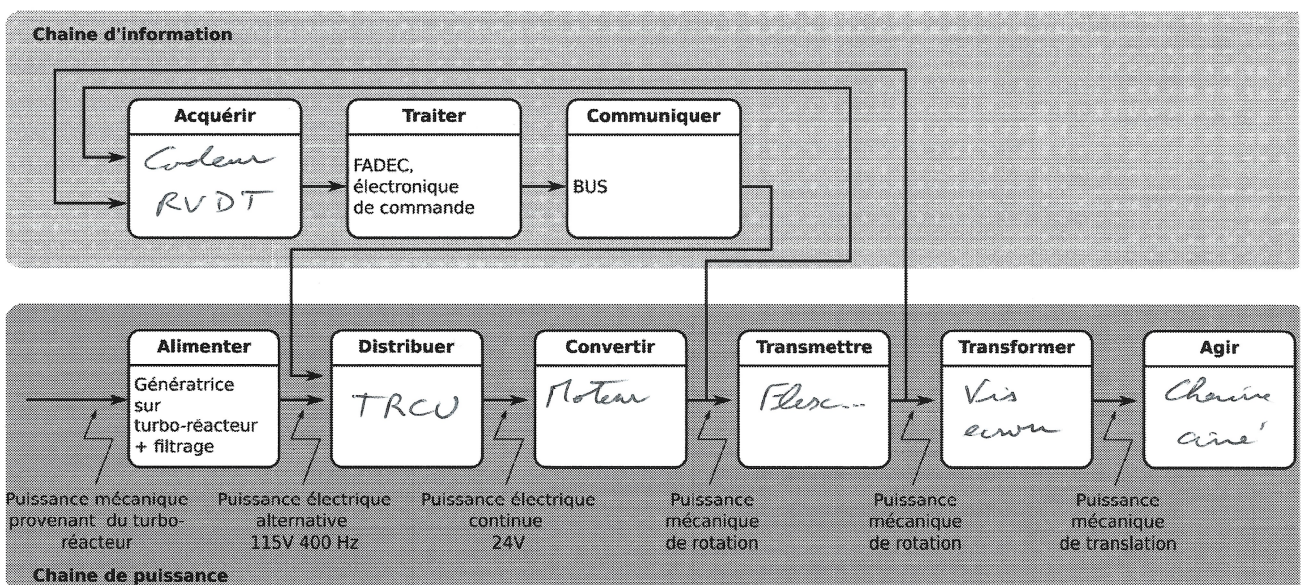
$H_{suete} = \frac{\frac{KJ}{K_{in}^2} \lambda^2 + \frac{RJ}{K_{in}^2} \lambda + 1}{\lambda^2 + \frac{R}{J} \lambda + \frac{R+K_{in}^2}{J}}$

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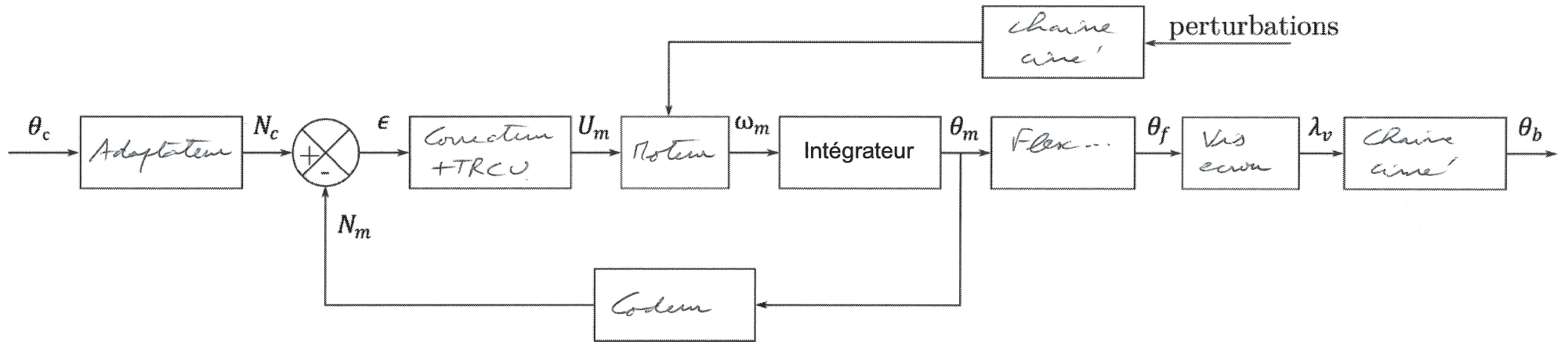
Exercice 3.



Exercice 4, question 1.



Exercice 4, question 2.



Exercice 4, question 4.

