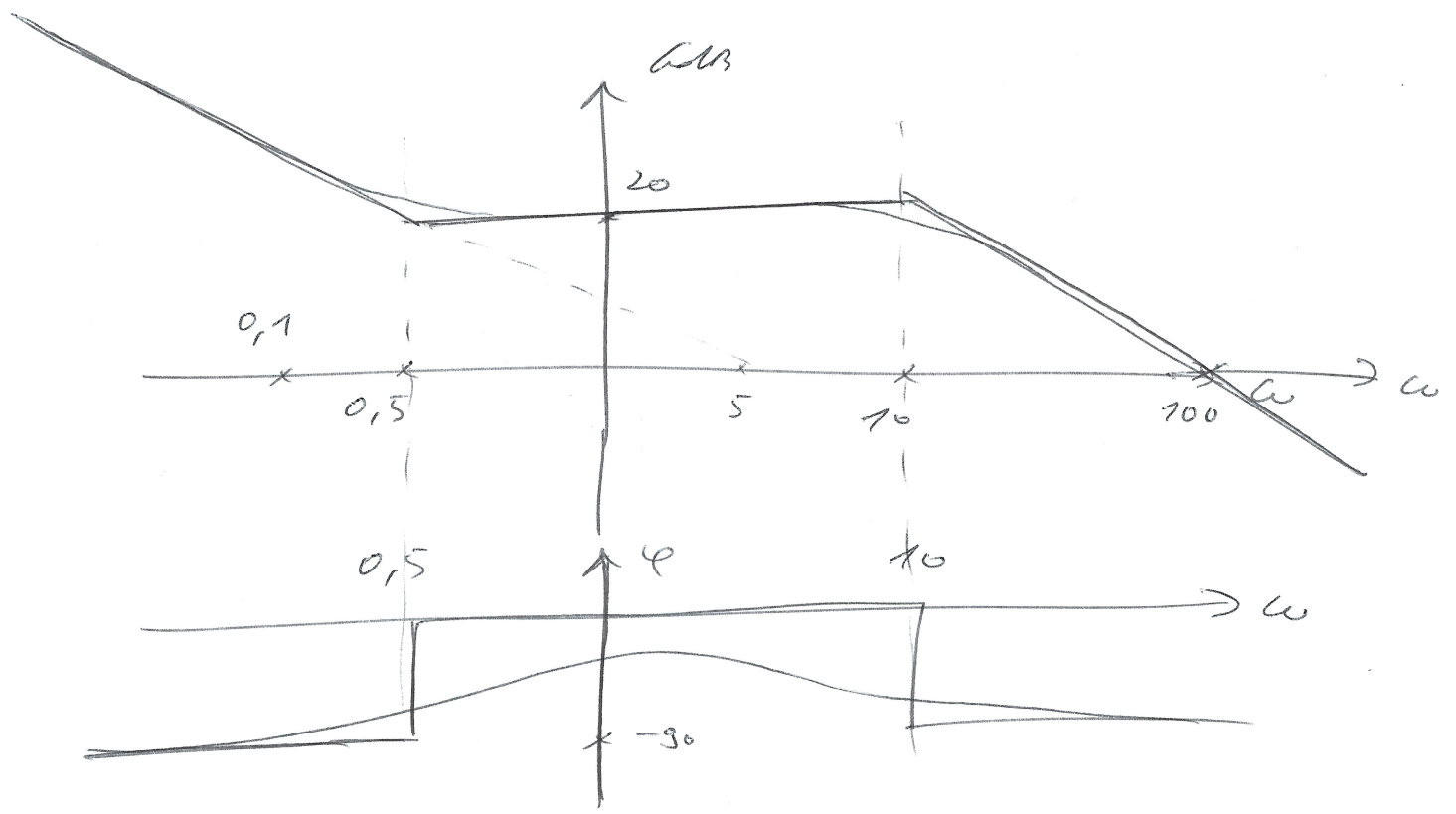


DS de SE, PPS17, janvier 25.

Exo 1

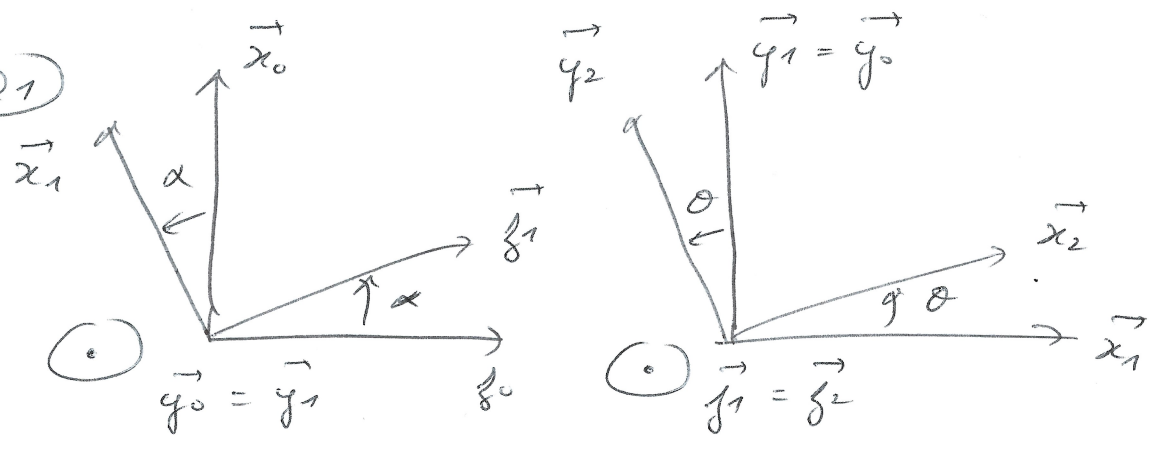
$$H(\lambda) = \frac{5(1+2\lambda)}{\lambda(1+0,1\lambda)}$$

Casuses $\omega = 0,5$ et 10



Exo 2

Q1



Q2

$$\vec{OD} = \vec{OA} + \vec{AD} = -a\vec{x}_1 + (b+\lambda)\vec{x}_2$$

$$\left(\frac{d\vec{x}_2}{dt}\right)_0 = \left(\frac{d\vec{x}_2}{dt}\right)_1 + \sqrt{2} \vec{1}_0 \cdot \vec{x}_2 = \dot{\theta} \vec{y}_2 + \dot{\alpha} \vec{y}_1 \cdot (\cos\theta \vec{x}_1 + \sin\theta \vec{y}_1) = \dot{\theta} \vec{y}_2 - \dot{\alpha} \cos\theta \vec{f}_1$$

$$\vec{v}(\partial E \%) = a \dot{\alpha} \vec{f}_1 + \dot{\lambda} \vec{x}_2 + (b+\lambda)(\dot{\theta} \vec{y}_2 - \dot{\alpha} \cos\theta \vec{f}_1)$$

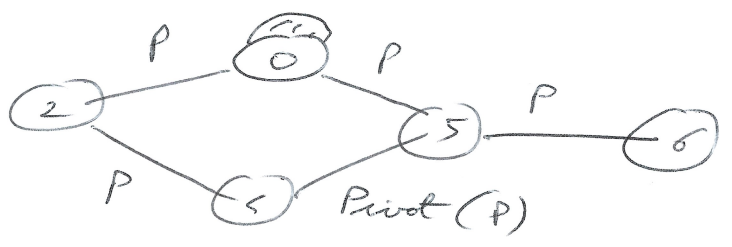
Q3

$$\vec{OE} = -a\vec{x}_1 + (b+\lambda)\vec{x}_2 + c\vec{x}_1$$

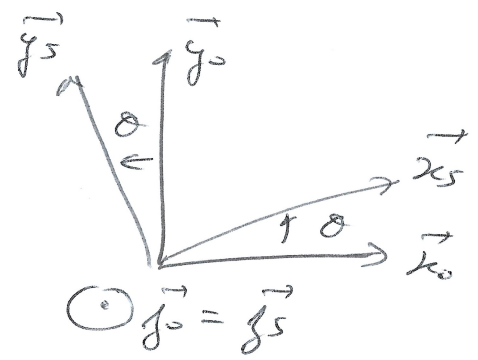
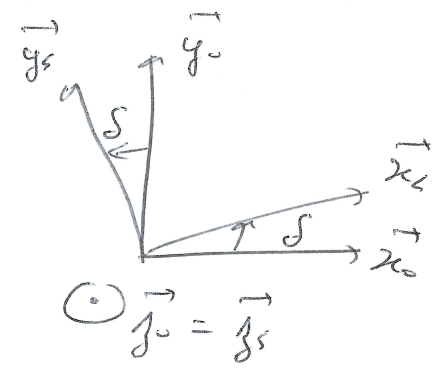
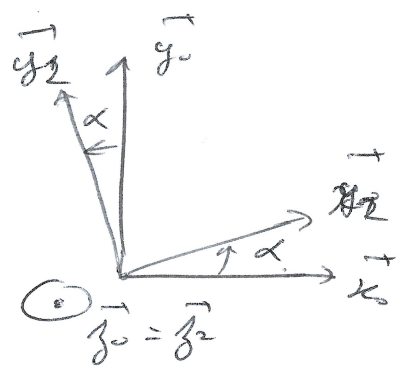
② $\vec{OE} = [c - a + (b + \lambda) \cos \theta] \vec{x}_1 + (b + \lambda) m \theta \vec{y}_1$

Il faut : $\begin{cases} c - a + (b + \lambda) \cos \theta = -d \\ \lambda m \theta + (b + \lambda) \theta' \cos \theta = v \end{cases}$

Exo 3 Buggy (Q1)



Q2



Q3 $\vec{EA} + \vec{AH} = \vec{EG} + \vec{GH}$

$c \vec{y}_2 + a \vec{x}_0 + b \vec{y}_0 = d \vec{x}_5 + e \vec{x}_5 + l \vec{y}_5$

$$\left\{ \begin{array}{l} \vec{y}_2 = -m \sin \alpha \vec{x}_0 + \cos \alpha \vec{y}_0 \\ \vec{x}_4 = \cos \delta \vec{x}_0 + m \sin \delta \vec{y}_0 \\ \vec{x}_5 = \cos \theta \vec{x}_0 + m \sin \theta \vec{y}_0 \\ \vec{y}_5 = -\sin \theta \vec{x}_0 + \cos \theta \vec{y}_0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} -c m \sin \alpha + a = d \cos \theta + e \cos \theta - l m \sin \theta \\ c \cos \alpha + b = d m \sin \theta + e m \sin \theta + l \cos \theta \end{array} \right.$$

$d \cos \theta = \dots$

$d m \sin \theta = \dots$

$d^2 = (a - c m \sin \alpha - e \cos \theta + l m \sin \theta)^2 + (c \cos \alpha + b - e m \sin \theta - l \cos \theta)^2 = A^2 + B^2$

Q4 $\vec{v}(I \in \Sigma_0) = \left(\frac{d \vec{HI}}{dt} \right)_0$ $\vec{HI} = g \vec{x}_5 - h \vec{y}_5$

$\vec{v}(I \in \Sigma_0) = g \dot{\theta} \vec{y}_5 + h \dot{\theta} \vec{x}_5$