

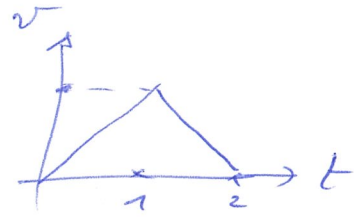
①

Correction DV de SI, NP, nov 22

Sujet Centrale NP 22, "SLED"

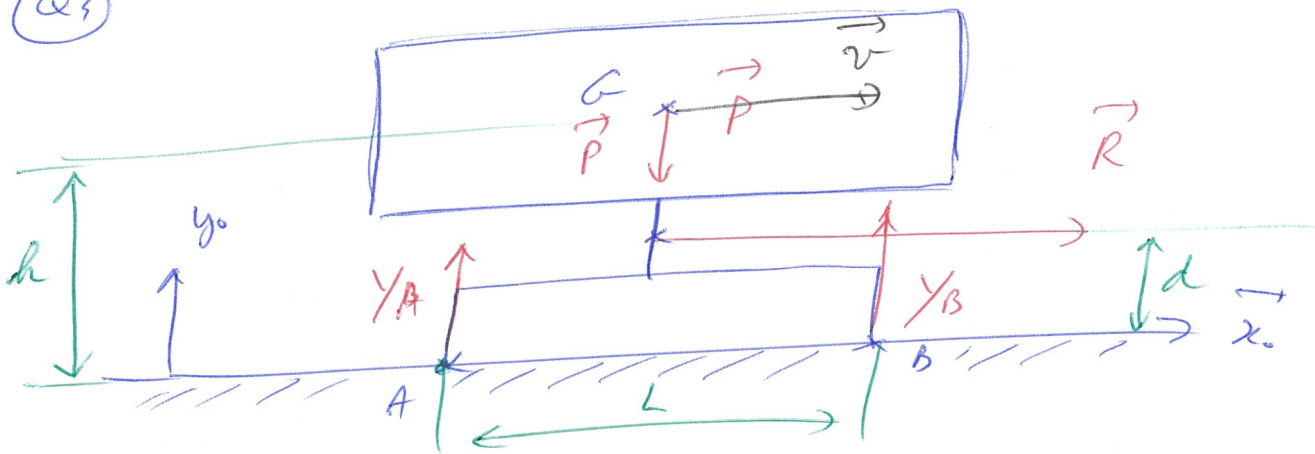
Q1 $a_c = 0,3 \cdot g = 2,943 \text{ m/s}^2$

Q2 $v(t) = 0,3gt$; $v(1) = 2,943 \text{ m/s}$



Q3 $x_{\text{max}} = 2,943 \text{ m}$ (aire de la courbe)

Q4



Q5 $\vec{S}(G, S/S_0) = \vec{0}$

$$\begin{aligned} \vec{S}(A, S/S_0) &= \vec{S}(G, S/S_0) + \vec{AG} \wedge m \cdot \vec{a}_c \\ &= \vec{0} + \left(\frac{L}{2} \vec{x}_0 + h \vec{y}_0 \right) \wedge m a_c \vec{x}_0 = -m a_c h \vec{y}_0 \end{aligned}$$

Q6 TTD a A $\Rightarrow -m a_c h = L Y_B - m g \frac{L}{2} - d R$

$$\Rightarrow Y_B = \frac{m g}{2} + \frac{d R}{L} - \frac{m a_c h}{L}$$

Q7 Non basculement $\Rightarrow Y_B > 0$

Q8 En role S, PRD sur $\vec{x}_0 \Rightarrow R = m \cdot a_c$

Q9 $Y_B > 0 \Rightarrow \dots \Rightarrow L > \frac{2a}{g} (h-d) = L_{\text{min}}$

Q10 L_{min} independant de m .

Q11 $L_{\text{min}} = 528 \text{ mm}$

Q12 $x + L_{\text{min}} = 3,428 < 4,5 \text{ m}$

② "SLED" motor (partin TEC)

③ Q36 $k = \frac{\omega_1}{\omega_2} = \frac{D_2}{D_1} = \frac{100}{35}$

③ Q37 $v = \frac{D_3}{2} \omega_2$ $\omega_2 = \frac{D_1}{D_2} \omega_1 \Rightarrow v = \frac{D_1}{2} \omega_1$

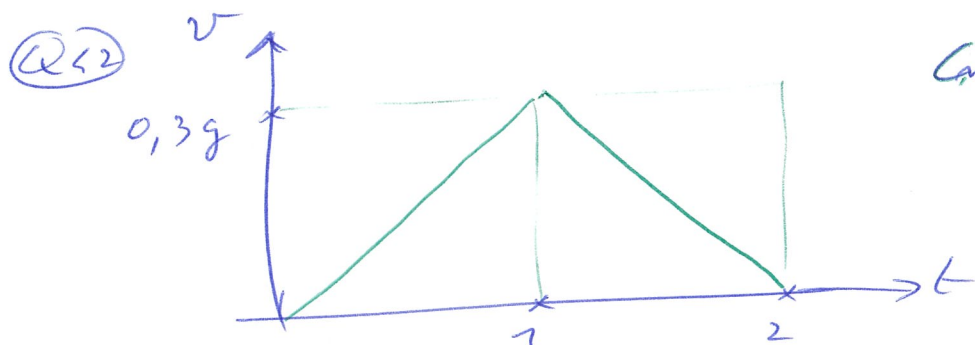
③ Q38 $E(\frac{E}{s_0}) = \frac{1}{2} m_{ms} v^2 + \frac{1}{2} J_1 \omega_1^2 + \frac{1}{2} J_2 \omega_2^2$

$E(\frac{E}{s_0}) = \frac{1}{2} \underbrace{\left[m_{ms} \left(\frac{D_1}{2}\right)^2 + J_1 + J_2 \left(\frac{D_1}{D_2}\right)^2 \right]}_{J_{eq}} \omega_1^2$

③ Q40 $J_{eq} \dot{\omega}_1 \omega_1 = \eta C_m \omega_1 = \underbrace{C_m \omega_1}_{\text{Pent}} - \underbrace{(1-\eta) C_m \omega_1}_{\text{Pint}}$

$\Rightarrow J_{eq} \dot{\omega}_1 = \eta C_m \Rightarrow C_m = \frac{J_{eq}}{\eta} \dot{\omega}_1$

③ Q41 $\omega_1 = \frac{2}{D_1} v \Rightarrow C_m = \frac{2 J_{eq}}{\eta D_1} v$



$C_{m \text{ motor}} = 32 \text{ Nm}$

$C_{m \text{ motor}} = \frac{2 J_{eq}}{\eta D_1} \times v_{\text{max}} = 19,6 \text{ Nm}$