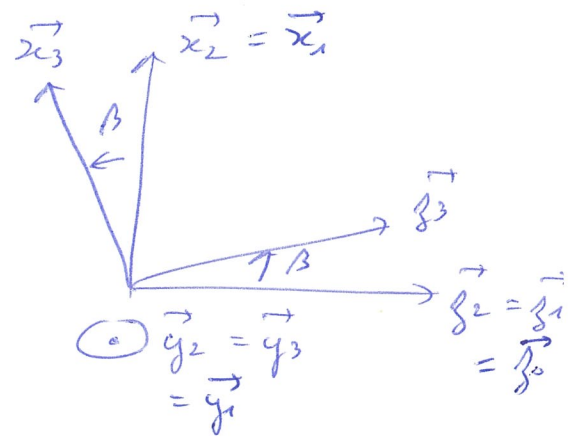


①

Exo 1

Conexion DB



$$\textcircled{Q1} \quad \vec{v}(t \in \mathbb{R}) =$$

$$\vec{OG} = \lambda \vec{f}_0 + a \vec{x}_1 + l \vec{x}_3$$

$$\left(\frac{d\vec{x}_3}{dt} \right)_0 = \left(\frac{d\vec{x}_3}{dt} \right)_2 + \vec{\Omega}_{0/2} \wedge \vec{x}_3$$

$$= -\dot{\beta} \vec{f}_3 + \dot{\alpha} \vec{f}_1 \wedge \vec{x}_3$$

$$= -\dot{\beta} \vec{f}_3 + \dot{\alpha} \cos \beta \vec{y}_2 \quad (\times l)$$

$$\vec{v}(t \in \mathbb{R}) = \lambda \dot{\vec{f}}_0 + a \dot{\alpha} \vec{y}_1 - l \dot{\beta} \vec{f}_3 + l \dot{\alpha} \cos \beta \vec{y}_2$$

$$\left(\frac{d\vec{f}_3}{dt} \right)_0 = \left(\frac{d\vec{f}_3}{dt} \right)_2 + \vec{\Omega}_{0/2} \wedge \vec{f}_3$$

$$= \dot{\beta} \vec{x}_3 + \dot{\alpha} \vec{f}_1 \wedge \vec{f}_3$$

$$= \dot{\beta} \vec{x}_3 + \dot{\alpha} \sin \beta \vec{y}_2 \quad (\times -l\dot{\beta})$$

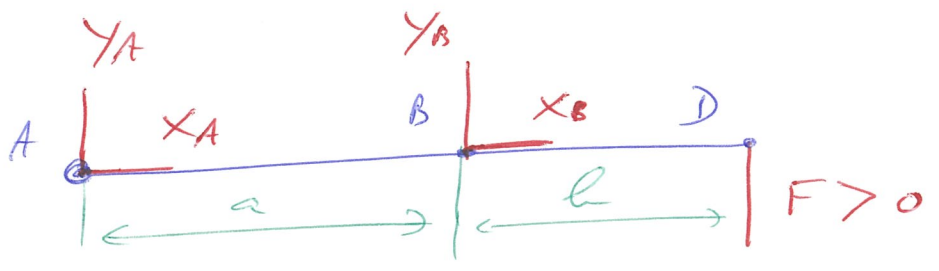
$$\vec{a}(t \in \mathbb{R}) = \ddot{\lambda} \vec{f}_0 + a \ddot{\alpha} \vec{y}_1 - a \dot{\alpha}^2 \vec{x}_1 - l \ddot{\beta} \vec{f}_3$$

$$- l \dot{\beta}^2 \vec{x}_3 - l \dot{\alpha} \dot{\beta} \sin \beta \vec{y}_2 + l \dot{\alpha} \cos \beta \vec{y}_2 - l \dot{\alpha} \dot{\beta} \sin \beta \vec{y}_2$$

$$- l \dot{\alpha}^2 \cos \beta \vec{x}_2$$

② Exo 2

On isole ②



$$\begin{cases} Y_A + Y_B = F \\ X_A + X_B = 0 \\ Y_B \times a - F \times (a+l) = 0 \end{cases} \quad (\text{actions sur } (2))$$

$$\Rightarrow Y_B = \frac{a+l}{a} \cdot F$$

$$Y_A = F - Y_B = -\frac{l}{a} F$$

On isole ①: solide soumis à 2 forces
(solide ① orienté à 45°)

Rem: Y_B et X_B actions de (1) → (2).

$$X_B = Y_B$$

X_C et Y_C actions de (0) → (1).

$$X_C = X_B = Y_C = Y_B$$

③ Pl Encosquelette lombaire

Q1 Avec $< 0 N$, on divise par 2 les pressions ...

Q2 Avant 20 %

Arrière 45 %

Année 25 %

Q3 $\vec{OC} + \vec{CD} = \vec{OE} + \vec{ED}$

$$h \vec{y} + b \vec{x}_3 = a \vec{x} + l_2 \vec{y}_2$$

$$\vec{x}_3 = \cos \varphi \vec{x} + \sin \varphi \vec{y} \quad (\times b)$$

$$\vec{y}_2 = -\sin \beta \vec{x} + \cos \beta \vec{y} \quad (\times l_2)$$

$$b \cos \varphi = a - l_2 \sin \beta$$

$$h + b \sin \varphi = l_2 \cos \beta$$

$$l_2 \cos \beta = h + b \sin \varphi$$

$$l_2 \sin \beta = a - b \cos \varphi$$

$$l_2(\varphi) = \sqrt{(h + b \sin \varphi)^2 + (a - b \cos \varphi)^2}$$

Q4 $a = 100 \text{ mm}$; $b = 150 \text{ mm}$; $h_0 = 100 \text{ mm}$; $\Delta h = 50 \text{ mm}$.

$$\bar{a} \text{ } t=0 \Rightarrow \varphi = 0 \Rightarrow l_2 = 111,8 \text{ mm}$$

$$\bar{a} \text{ } t=T \Rightarrow \varphi = 20^\circ \Rightarrow l_2 = 205,8 \text{ mm}$$

$$\Rightarrow \Delta l_2 = 205,8 - 111,8 = 93,6 \text{ mm}$$